

# PHM5

## CANOPEN ABSOLUTE MULTI-TURN ENCODERS



- 58mm encoder, extra-flat
- Ø 6 & Ø 10 mm solid shaft version
- Robustness and excellent resistance to shocks / vibrations
- High protection levwel IP65
- High performances in temperature –20°C to 85° (-30°C option)
- Universal power supply from 5 to 30 Vdc
- High resolutions up to 8192 points pre turn (2<sup>13</sup>)
- Turns numerisation up to 65 536 (16 bits)



## Mechanical

	Cover : treated steel				
Material	Body : aluminum				
	Shaft : stainless steel				
Bearings	6 000 serie				
Maximum loads	Axial: 50 N				
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Shaft inertia	≤ 1.10-6 kg.m <sup>2</sup>				
Torque	≤ 4.10-3 N.m				
Permissible max. speed	6 000 min <sup>-1</sup>				
Continuous max. speed	6 000 min <sup>-1</sup>				
Shock (EN60068-2-27)	≤ 500 m.s <sup>-2</sup> (during 6 ms)				
Vibration (EN60068-2-6)	≤ 100 m.s <sup>-2</sup> (10 2 000 Hz)				
EMC	EN 61000-6-4, EN 61000-6-2				
Isolation	500V (1 min.)				
Weight (connector)	0,520 kg				
Operating temperature	- 20 + 85 °C (encoder T°)				
Storage temperature	- 20 + 85 °C				
Protection(EN 60529)	IP 65 (IP67 with flange option)				
Theoretical mechanical lifetime 10 <sup>9</sup> turns (Faxial / Fradial)	25 N / 50 N : 99				
Theoretical mechanical methile to turns (raxial) riadial)	50 N / 100 N : 12				



#### Electrical

Power supply	5 – 30Vdc		
Introduction	<1s		
Consumption (without load)	< 50mA (at 24Vdc)		
Accuracy	± ½ LSB (13 bits)		



## PROGRAMMABLE PARAMETERS

**Resolution:** defines the resolution per revolution (0 to 8 192)

Global resolution: total amount of codes for the encoder (2 to 536 870 912)

Transmission speed: programmable from 10kBaud (1000m) to 1 Mbaud (40 m); value per default: 20 Kbaud

**Address:** define the software address of the encoder on the bus (1 to 127, value by default: id = 1)

**Direction:** define the direction of count of the encoder

RAX: defines the value of its preset position (non turning shaft)

**CAM**: Low and High Limits



# COMMUNICATION MODES

3 modes are available to interrogate the encoder:

POLLING mode: (Response to a RTR message): The position value is only given upon request (SDO mode)

**CYCLIC mode:** the encoder transmits its position in an asynchronous manner. The frequency of the transmission is defined by the programmable cyclical timer register from 0 to 65 535 ms

**SYNCHRO mode:** the encoder transmits its position on a synchronous demand by the master



### **CANOPEN CONNECTION**

1	2	3	4	5	6	7	8,9,11	10	12
Reserved	CAN LOW	CAN GND	Reserved	Reserved	Reserved	CAN HIGH	Reserved	OV	+ 5/30Vdc

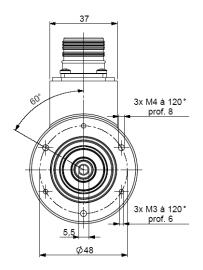
Pinout 3 (CAN GND) and 10 (0V) are connected together (intern the encoder)

Note: Refer to the bus standards for the maximal derivation length

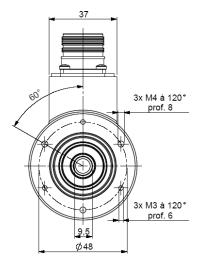


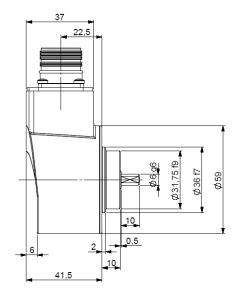


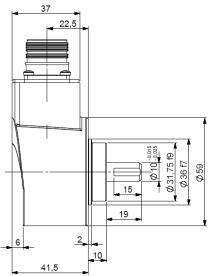
#### PHM5\_06 connection BCR (radial M23)

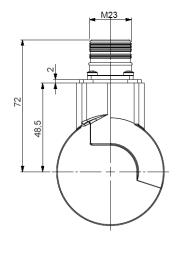


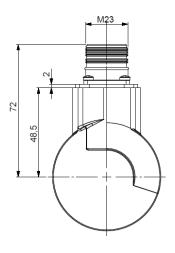
PHM5\_10 connection BCR (radial M23)





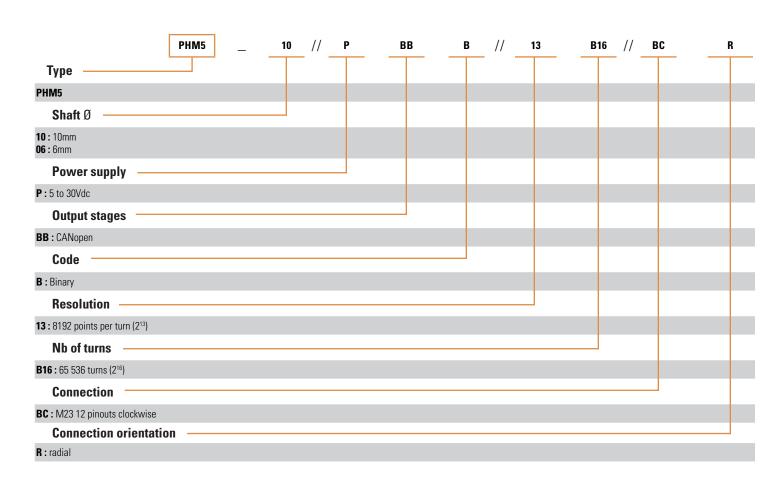








(Special versions upon request, for ex. special flanges/electronics/connections...)





## **AGENCY APPROVALS & CERTIFICATIONS**



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